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# Triggering Conditions and Data Quality Special Vehicle Warning

## CAR 2 CAR Communication Consortium



# CAR 2 CAR

## COMMUNICATION CONSORTIUM

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### About the C2C-CC

Enhancing road safety and traffic efficiency by means of Cooperative Intelligent Transport Systems and Services (C-ITS) is the dedicated goal of the CAR 2 CAR Communication Consortium. The industrial driven, non-commercial association was founded in 2002 by vehicle manufacturers affiliated with the idea of cooperative road traffic based on Vehicle-to-Vehicle Communications (V2V) and supported by Vehicle-to-Infrastructure Communications (V2I). The Consortium members represent worldwide major vehicle manufactures, equipment suppliers and research organisations.

Over the years, the CAR 2 CAR Communication Consortium has evolved to be one of the key players in preparing the initial deployment of C-ITS in Europe and the subsequent innovation phases. CAR 2 CAR members focus on wireless V2V communication applications based on ITS-G5 and concentrate all efforts on creating standards to ensure the interoperability of cooperative systems, spanning all vehicle classes across borders and brands. As a key contributor, the CAR 2 CAR Communication Consortium and its members work in close cooperation with the European and international standardisation organisations.

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## Document information

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**Table 1: Document information**

**Changes since last version**

Title:	<b>Triggering Conditions and Data Quality Special Vehicle Warning</b>		
Date	Changes	Edited by	Approved
2021-12-17	Added marking of requirements, indicating relevance for interoperability according to [CPOC]	Release Management	Steering Committee
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**Table 2: Changes since last version**

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## 1 Introduction

**Other (informational)**

**RS\_tcSpVe\_220**

This document describes the triggering conditions for the emergency vehicle warning. The vehicle C-ITS service is divided in the following three sub vehicle C-ITS services:

- 'special vehicle warning — emergency vehicle in operation';
- 'special vehicle warning — stationary safeguarding emergency vehicle';
- 'special vehicle warning — stationary recovery service warning'.

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## 2 Definitions

### Definition

RS\_tcSpVe\_642

'*Vehicle speed*' is the length of the velocity-vector of the reference position point.

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### 3 Requirement specifications

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**Requirement (i)** **RS\_tcSpVe\_242**

This vehicle C-ITS service deals with vehicles which are 'stationary'. A stationary vehicle is defined in RS\_BSP\_511

Tested by:

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#### 3.1 Special vehicle warning - emergency vehicle in operation

##### 3.1.1 Description of vehicle C-ITS service

**Other (informational)** **RS\_tcSpVe\_221**

An emergency vehicle is any vehicle that is designated and authorized to respond to an emergency. These vehicles are usually operated by designated agencies, often part of the government, but also run by charities, non-governmental organizations and some commercial companies. Emergency vehicles are often permitted by law to break conventional road rules in order to reach their destinations in the fastest possible time, such as (but not limited to) driving through an intersection when the traffic lights are red, or exceeding the speed limit.

**Other (informational)** **RS\_tcSpVe\_222**

This clause describes the triggering conditions for the emergency vehicles warning vehicle C-ITS service. The vehicle C-ITS service informs drivers of nearby vehicles about an emergency vehicle moving to an operation scene, which is signalled by the use of the light bar.

**Requirement (i)** **RS\_tcSpVe\_117**

As soon as the vehicle C-ITS service is triggered, a DENM shall be transmitted by the emergency vehicle C-ITS station and shall set data fields of CAM in accordance with the rules specified in the current clause.

Note: A parallel activation with the vehicle C-ITS service *Stationary Safeguarding Emergency Vehicle* has to be avoided. For an emergency vehicle C-ITS station the default vehicle C-ITS service is *Emergency Vehicle In Operation*.

Tested by:

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**Other (informational)** **RS\_tcSpVe\_224**

The following vehicle C-ITS services are related to this service, because they share similar triggering conditions:

- 'special vehicle warning — stationary safeguarding emergency vehicle';
- 'special vehicle warning — stationary recovery service warning'.

**Requirement (i)** **RS\_tcSpVe\_118**

The default vehicle C-ITS service for an emergency vehicle C-ITS station is '*emergency vehicle in operation*'. A change to the '*stationary safeguarding emergency vehicle*' vehicle C-ITS service shall be triggered only under the conditions set out in clause 3.2.

Tested by:

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### 3.1.2 Triggering conditions

#### 3.1.2.1 Preconditions

**Requirement (i)** **RS\_tcSpVe\_119**

The following preconditions shall be satisfied when this use case is triggered:

- the *stationType* is confirmed to be a special vehicle (*stationType* of CAM is set to *specialVehicles(10)*). The vehicle C-ITS service is restricted to emergency vehicles as prescribed in clause 3.1.1.
- the triggering conditions regarding ‘stationary safeguarding emergency vehicle’ shall not be satisfied, see clause 3.2.2

Tested by:

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#### 3.1.2.2 Service-specific conditions

**Requirement (i)** **RS\_tcSpVe\_120**

If the preconditions in RS\_tcSpVe\_119 and the following condition are satisfied, the generation of a DENM shall be triggered.

- a) the light bar is in use.

Tested by:

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**Requirement (i)** **RS\_tcSpVe\_121**

The level of information quality can be improved by the following conditions:

- b) the siren is in use
- c) the vehicle is not stationary.

Tested by:

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#### 3.1.2.3 Information quality

**Requirement (i)** **RS\_tcSpVe\_123**

The value of the data element *informationQuality* in the DENM depends on how the event is detected. The *informationQuality* value shall be set in accordance with the following table (highest possible value shall be used):

**Table 3: Information quality of ‘emergency vehicle in operation’**

Event detection	Value of InformationQuality
No TRCO-compliant implementation	unknown(0)
Condition a) is fulfilled	1
Conditions a) and b) are fulfilled	2
Conditions a) and c) are fulfilled	3
Conditions a), b), and c) are fulfilled	4

Tested by:

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**Requirement (i)**

RS\_tcSpVe\_124

If the triggering conditions change between two updates, the *informationQuality* shall not be changed until the next update. If the changed conditions are still fulfilled while the DENM is updated, the *informationQuality* shall be updated.

Tested by:

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**3.1.3 Termination conditions****Requirement (i)**

RS\_tcSpVe\_125

The vehicle C-ITS service shall be terminated when the light bar is no longer in use. At the termination of the vehicle C-ITS service, updating of DENMs shall be terminated. The *vehicleRole* shall be set to *default(0)* if the light bar is no longer in use.

Tested by:

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**3.1.3.1 Cancellation****Requirement (i)**

RS\_tcSpVe\_126

A cancellation DENM shall not be used for this vehicle C-ITS service.

Tested by:

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**3.1.3.2 Negation****Requirement (i)**

RS\_tcSpVe\_127

A negation DENM shall not be used for this vehicle C-ITS service.

Tested by:

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**3.1.4 Update****Requirement (i)**

RS\_tcSpVe\_128

The generated DENM shall be updated every 250 ms if the triggering conditions are still satisfied. The data fields that are assigned new values are defined in RS\_tcSpVe\_131.

Tested by:

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**3.1.5 Repetition duration and repetition interval****Requirement (i)**

RS\_tcSpVe\_129

A repetition of the DENM shall not be used for this vehicle C-ITS service.

Tested by:

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**3.1.6 Traffic class****Requirement (i)**

RS\_tcSpVe\_130

New and update DENMs shall be set to *traffic class 1*.

Tested by:

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### 3.1.7 Message parameters

#### 3.1.7.1 DENM

##### Requirement (i)

RS\_tcSpVe\_131

The following table specifies the data elements of the DENM that shall be set.

**Table 4: DENM data elements of ‘emergency vehicle in operation’**

Data field	Value										
<b>Management container</b>											
<i>actionID</i>	Identifier of a DENM. Shall be set in accordance with [TS 102 894-2].										
<i>detectionTime</i>	<i>Timestamp</i> ts-timestamp at which the event is detected by the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.										
<i>referenceTime</i>	<i>Timestamp</i> ts-timestamp at which a new DENM or an update DENM is generated. Shall be set in accordance with [TS 102 894-2].										
<i>termination</i>	Shall not be set, because neither negation nor cancellation are to be used in this vehicle C-ITS service.										
<i>eventPosition</i>	<i>ReferencePosition</i> . Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.										
<i>relevanceDistance</i>	lessThan1000m(4)										
<i>relevanceTrafficDirection</i>	If the roadType is known the value shall be set as follows: <table border="1" style="margin-left: 20px;"> <thead> <tr> <th>RoadType</th> <th>Direction</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>allTrafficDirections(0)</td> </tr> <tr> <td>1</td> <td>upstreamTraffic(1)</td> </tr> <tr> <td>2</td> <td>allTrafficDirections(0)</td> </tr> <tr> <td>3</td> <td>upstreamTraffic(1)</td> </tr> </tbody> </table> Otherwise, the value shall be set to allTrafficDirections(0)	RoadType	Direction	0	allTrafficDirections(0)	1	upstreamTraffic(1)	2	allTrafficDirections(0)	3	upstreamTraffic(1)
RoadType	Direction										
0	allTrafficDirections(0)										
1	upstreamTraffic(1)										
2	allTrafficDirections(0)										
3	upstreamTraffic(1)										
<i>validityDuration</i>	2 s										
<i>stationType</i>	specialVehicles(10)										
<b>Situation container</b>											
<i>informationQuality</i>	See RS_tcSpVe_123. Shall be refreshed for every update DENM.										
<i>causeCode</i>	emergencyVehicleApproaching (95)										
<i>subCauseCode</i>	emergencyVehicleApproaching(1)										

<b>Location container</b>																							
<i>eventSpeed</i>	Speed of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.																						
<i>eventPositionHeading</i>	Heading of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.																						
<i>traces</i>	<i>PathHistory</i> of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.																						
<i>roadType</i>	<p><i>RoadType</i> of the road the detecting vehicle C-ITS station is situated on. Shall be refreshed for an update DENM. Shall be set in accordance with [TS 102 894-2] in combination with the following rules:</p> <table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: center;">Urban / non-urban</th> <th style="text-align: center;">Structural separation</th> <th style="text-align: center;">Data element</th> </tr> </thead> <tbody> <tr> <td style="text-align: center;">Urban</td> <td style="text-align: center;">No</td> <td style="text-align: center;">urban-NoStructuralSeparationToOppositeLanes(0)</td> </tr> <tr> <td style="text-align: center;">Urban</td> <td style="text-align: center;">Yes</td> <td style="text-align: center;">urban-WithStructuralSeparationToOppositeLanes(1)</td> </tr> <tr> <td style="text-align: center;">Urban</td> <td style="text-align: center;">Unknown</td> <td style="text-align: center;">urban-NoStructuralSeparationToOppositeLanes(0)</td> </tr> <tr> <td style="text-align: center;">Non-urban</td> <td style="text-align: center;">No</td> <td style="text-align: center;">nonUrban-NoStructuralSeparationToOppositeLanes(2)</td> </tr> <tr> <td style="text-align: center;">Non-urban</td> <td style="text-align: center;">Yes</td> <td style="text-align: center;">nonUrban-WithStructuralSeparationToOppositeLanes(3)</td> </tr> <tr> <td style="text-align: center;">Non-urban</td> <td style="text-align: center;">Unknown</td> <td style="text-align: center;">nonUrban-NoStructuralSeparationToOppositeLanes(2)</td> </tr> </tbody> </table> <p>Otherwise, if the information about the urban/non-urban status cannot be determined, the data element shall be omitted.</p>		Urban / non-urban	Structural separation	Data element	Urban	No	urban-NoStructuralSeparationToOppositeLanes(0)	Urban	Yes	urban-WithStructuralSeparationToOppositeLanes(1)	Urban	Unknown	urban-NoStructuralSeparationToOppositeLanes(0)	Non-urban	No	nonUrban-NoStructuralSeparationToOppositeLanes(2)	Non-urban	Yes	nonUrban-WithStructuralSeparationToOppositeLanes(3)	Non-urban	Unknown	nonUrban-NoStructuralSeparationToOppositeLanes(2)
Urban / non-urban	Structural separation	Data element																					
Urban	No	urban-NoStructuralSeparationToOppositeLanes(0)																					
Urban	Yes	urban-WithStructuralSeparationToOppositeLanes(1)																					
Urban	Unknown	urban-NoStructuralSeparationToOppositeLanes(0)																					
Non-urban	No	nonUrban-NoStructuralSeparationToOppositeLanes(2)																					
Non-urban	Yes	nonUrban-WithStructuralSeparationToOppositeLanes(3)																					
Non-urban	Unknown	nonUrban-NoStructuralSeparationToOppositeLanes(2)																					
<b>Alacarte container</b>																							
<i>lanePosition</i>	If the lanePosition is provided by an on-board sensor (e.g. radar, camera), the value shall be set in accordance with [TS 102 894-2]. Use of GNSS and a digital map to estimate the lane number is not legitimate for this version of the triggering condition.																						

	If the lanePosition is unknown, the data element shall be omitted. Shall be refreshed for an update DENM.
<b>Alacarte container: StationaryVehicleContainer</b>	
<i>stationarySince</i>	Shall be set according to the duration in minutes of the detecting vehicle C-ITS station being stationary. Shall be set in accordance with [TS 102 894-2].  Shall be refreshed for an update DENM.

Tested by:

### 3.1.7.2 CAM

#### Requirement (i)

**RS\_tcSpVe\_132**

The *vehicleRole* shall be initialised at a 'default' setting (*vehicleRole* of CAM set to *default(0)*). If at least one of the triggering conditions in RS\_tcSpVe\_120 is satisfied, the *vehicleRole* shall be set to *emergency(6)*.

Tested by:

#### Requirement (i)

**RS\_tcSpVe\_133**

The following table specifies the data elements of the CAM that shall be set if the vehicle C-ITS service is triggered.

**Table 5: CAM data elements of 'emergency vehicle in operation'**

Data field	Value
<b>CoopAwareness</b>	
<i>generationDeltaTime</i>	Time corresponding to the time of the reference position in the CAM, considered as time of CAM generation.  Shall be set in accordance with [EN 302 637-2].
<b>BasicContainer</b>	
<i>stationType</i>	specialVehicles(10)
<i>referencePosition</i>	Position and position accuracy measured at the reference point of the originating vehicle C-ITS station.  Shall be set in accordance with [TS 102 894-2].
<b>HighFrequencyContainer shall be set to BasicVehicleContainerHighFrequency</b>	
<i>heading</i>	Heading direction of the originating vehicle C-ITS station in relation to true north.  Shall be set in accordance with [TS 102 894-2].
<i>speed</i>	Driving speed of the originating vehicle C-ITS station.  Shall be set in accordance with [TS 102 894-2].
<i>driveDirection</i>	Vehicle drive direction (forward or backward) of the originating vehicle C-ITS station.

	Shall be set in accordance with [TS 102 894-2].
<i>vehicleLength</i>	Length of vehicle. Shall be set in accordance with [TS 102 894-2].
<i>vehicleWidth</i>	Width of vehicle. Shall be set in accordance with [TS 102 894-2].
<i>longitudinalAcceleration</i>	Vehicle longitudinal acceleration of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2].
<i>curvature</i>	Curvature of the vehicle trajectory and the accuracy. Shall be set in accordance with [TS 102 894-2].
<i>curvatureCalcMode</i>	Describes whether the yaw rate is used to calculate the curvature for a reported curvature value. Shall be set in accordance with [TS 102 894-2].
<i>yawRate</i>	Yaw rate of vehicle at a point in time. Shall be set in accordance with [TS 102 894-2].
<b>LowFrequencyContainer shall be set to BasicVehicleContainerLowFrequency</b>	
<i>vehicleRole</i>	emergency(6)
<i>exteriorLights</i>	Describes the status of the exterior light switches of a vehicle. Shall be set in accordance with [TS 102 894-2].
<i>pathHistory</i>	Represents the vehicle's movement over a recent period and/or distance. Shall be set in accordance with [TS 102 894-2].
<b>SpecialVehicleContainer shall be set to EmergencyContainer</b>	
<i>lightBarSirenInUse</i>	lightBarActivated bit shall be set to 1(onChange), if the usage of the light bar is detected; otherwise, it shall be set to 0. sirenActivated bit shall be set to 1, if usage of the siren is detected; otherwise, it shall be set to 0.
<i>emergencyPriority</i>	Is not required
<i>causeCode</i>	As specified in DENM (RS_tcSpVe_131)
<i>subCauseCode</i>	As specified in DENM (RS_tcSpVe_131)

Tested by:

### 3.1.8 Network and transport layer

#### Requirement (i)

RS\_tcSpVe\_134

The interface parameter destination area in IF.DEN.1 [ETSI EN 302 637-3] shall be equal to a circular shape with centre point equal to *eventPosition* and radius equal to *relevanceDistance*.

Tested by:

### 3.1.9 Security layer

#### Requirement (i)

RS\_tcSpVe\_136

When the triggering conditions as described in clause 3.1.2 apply, the application shall request the blocking of the AT changeover as defined in RS\_BSP\_184.

Tested by:

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## 3.2 Special vehicle warning - stationary safeguarding emergency vehicle

### 3.2.1 Description of vehicle C-ITS service

#### Other (informational)

RS\_tcSpVe\_225

The emergency vehicle safeguards a stationary hazard area, e.g. caused by an accident or fire.

In this vehicle C-ITS service, the C2C-CC Basic System informs the driver of an emergency vehicle safeguarding a stationary hazard area.

#### Requirement (i)

RS\_tcSpVe\_137

As soon as the vehicle C-ITS service is triggered, the Stationary safeguarding emergency vehicle shall transmit a DENM and shall set data fields of CAM in accordance with the rules specified in the current clause.

Note: A parallel activation with the vehicle C-ITS service *Emergency Vehicle in Operation* has to be avoided, i.e. an emergency vehicle C-ITS station can be either triggered as an *Emergency Vehicle in Operation* or as a *Stationary Safeguarding Emergency Vehicle*.

Tested by:

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#### Other (informational)

RS\_tcSpVe\_227

The following vehicle C-ITS services are related to this service, because they share similar triggering conditions:

- 'special vehicle warning — emergency vehicle in operation';
- 'special vehicle warning — stationary recovery service warning'.

### 3.2.2 Triggering conditions

#### 3.2.2.1 Preconditions

#### Requirement (i)

RS\_tcSpVe\_138

The following preconditions shall be satisfied when this use case is triggered:

- the *stationType* is confirmed to be an emergency vehicle (*stationType* of CAM is set to *specialVehicles(10)*). The vehicle C-ITS service is restricted to emergency vehicles as prescribed in clause 3.1.1.

Tested by:

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**Requirement (i)****RS\_tcSpVe\_139**

The default vehicle C-ITS service for an emergency vehicle C-ITS station is 'emergency vehicle in operation'. A change to the vehicle C-ITS service 'stationary safeguarding emergency vehicle' shall be triggered only under the conditions defined in clause 3.2.2.2.

Tested by:

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**3.2.2.2 Service-specific conditions****Requirement (i)****RS\_tcSpVe\_140**

If the vehicle is stationary and the light bar is in use, a *Standstill Timer* shall be initialised with zero and started. If the light bar is no longer in use or the vehicle is no longer stationary, the *Standstill Timer* shall be stopped and reset to zero.

Tested by:

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**Requirement (i)****RS\_tcSpVe\_240**

If the preconditions in RS\_tcSpVe\_138 and at least one of the following conditions are satisfied, the triggering conditions for this vehicle C-ITS service are fulfilled and the generation of a DENM shall be triggered:

- a) the light bar is in use and engine relay is activated;
- b) the light bar is in use, the hazard lights are activated and the vehicle's state suggests parking mode. (parking brake activated in case of manual transmission cars, 'park' selected in case of automatic transmission cars, stand is being used in case of PTWs);
- c) the light bar is in use, the hazard lights are activated and the *Standstill Timer* is 60 s or more.

Tested by:

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**Requirement (i)****RS\_tcSpVe\_143**

The level of information quality can be improved by the following conditions:

- d) the status of at least one door, or the boot, is 'open';
  - d.1) in case of PTWs, the status of the locked storage space is 'open';
- e) the driver's seat is detected, by a state-of-the-art technique for seat occupation, as being 'not occupied'.

Tested by:

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**Requirement (i)****RS\_tcSpVe\_144**

If the vehicle C-ITS service is triggered due to fulfilment of condition a) or b), the *Standstill Timer* shall be stopped and set to 60 s. In the update phase, only the conditions shall be checked, but no timer shall be started.

Tested by:

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**3.2.2.3 Information quality****Requirement (i)****RS\_tcSpVe\_145**

The value of the data element *informationQuality* in the DENM depends on how the event is



detected. The *informationQuality* value shall be set in accordance with the following table (highest possible value shall be used):

**Table 6: Information quality of ‘stationary safeguarding emergency vehicle’**

Event detection	Value of InformationQuality
No TRCO-compliant implementation	unknown(0)
Condition c) fulfilled	1
Condition b) fulfilled	2
At least one of conditions b) or c) fulfilled and condition d) fulfilled	3
At least one of conditions b) or c) fulfilled and condition e) fulfilled	4
Condition a) fulfilled	5

Tested by:

**Requirement (i)**

**RS\_tcSpVe\_146**

If the triggering conditions change between two updates, the *informationQuality* shall not be changed until the next update. If the changed conditions are still fulfilled while the DENM is updated, the *informationQuality* shall be updated.

Tested by:

**3.2.3 Termination conditions**

**Requirement (i)**

**RS\_tcSpVe\_147**

This vehicle C-ITS service is terminated by a cancellation of the originating vehicle C-ITS station. At the termination of the vehicle C-ITS service, update DENM request shall be terminated.

Tested by:

**3.2.3.1 Cancellation**

**Requirement (i)**

**RS\_tcSpVe\_148**

If the following condition is satisfied before the period set in the data element *validityDuration* has expired, the generation of a cancellation DENM shall be triggered:

- all the vehicle C-ITS service specific conditions a) to c) in clause 3.2.2.2 are no longer satisfied.

The *vehicleRole* shall be set to *default(0)* if the light bar is no longer in use.

Tested by:

**3.2.3.2 Negation**

**Requirement (i)**

**RS\_tcSpVe\_149**

A negation DENM shall not be used for this vehicle C-ITS service.

Tested by:

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### 3.2.4 Update

#### Requirement (i)

RS\_tcSpVe\_150

The generated DENM shall be updated every 60 s, if the triggering conditions are still satisfied. All data fields that are assigned new values are defined in RS\_tcSpVe\_153.

Tested by:

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### 3.2.5 Repetition duration and repetition interval

#### Requirement (i)

RS\_tcSpVe\_151

DENMs that are new, have been updated or have been cancelled shall be repeated for a *repetitionDuration* of 60 s with a *repetitionInterval* of 1 s. Therefore, the interface parameters *Repetition duration* and *Repetition interval* between the application and the DEN basic service shall be set in accordance with the above values.

Note: The *validityDuration* is set to 180 s. Therefore, one can prevent a gap of DENMs if the *repetitionDuration* of the original DENM has expired and the update has not yet been received.

Note: Where two DENMs with the same *causeCode* originate from the same vehicle C-ITS station, the case shall be managed by the receiving C-ITS station.

Tested by:

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### 3.2.6 Traffic class

#### Requirement (i)

RS\_tcSpVe\_152

New, update and cancellation DENMs shall be set to *traffic class* 1.

Tested by:

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### 3.2.7 Message parameters

#### 3.2.7.1 DENM

#### Requirement (i)

RS\_tcSpVe\_153

The following table specifies the data elements of the DENM that shall be set.

**Table 7: DENM data elements of 'stationary safeguarding emergency vehicle'**

Data field	Value
<b>Management container</b>	
<i>actionID</i>	Identifier of a DENM. Shall be set in accordance with [TS 102 894-2].
<i>detectionTime</i>	<i>Timestamp</i> ts-timestamp at which the event is detected by the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2].

	Shall be refreshed for an update DENM.										
<i>referenceTime</i>	<i>Timestamp</i> ts-timestamp at which a new, update or cancellation DENM is generated. Shall be set in accordance with [TS 102 894-2].										
<i>termination</i>	Shall not be set in the case of new or update DENM. Shall be set to isCancellation(0) in the case of fulfilment of cancellation conditions; see RS_tcSpVe_148.										
<i>eventPosition</i>	<i>ReferencePosition</i> . Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.										
<i>relevanceDistance</i>	lessThan5km(5)										
<i>relevanceTrafficDirection</i>	If the roadType is known, the value shall be set as follows: <table border="1" data-bbox="531 779 1013 1032"> <thead> <tr> <th>RoadType</th> <th>Direction</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>allTrafficDirections(0)</td> </tr> <tr> <td>1</td> <td>upstreamTraffic(1)</td> </tr> <tr> <td>2</td> <td>allTrafficDirections(0)</td> </tr> <tr> <td>3</td> <td>upstreamTraffic(1)</td> </tr> </tbody> </table> Otherwise, the value shall be set to allTrafficDirections(0)	RoadType	Direction	0	allTrafficDirections(0)	1	upstreamTraffic(1)	2	allTrafficDirections(0)	3	upstreamTraffic(1)
RoadType	Direction										
0	allTrafficDirections(0)										
1	upstreamTraffic(1)										
2	allTrafficDirections(0)										
3	upstreamTraffic(1)										
<i>validityDuration</i>	180 s										
<i>stationType</i>	specialVehicles(10)										
<b>Situation container</b>											
<i>informationQuality</i>	See RS_tcSpVe_145. Shall be refreshed for every update DENM.										
<i>causeCode</i>	rescueAndRecoveryWorkInProgress(15)										
<i>subCauseCode</i>	emergencyVehicles(1)										
<b>Location container</b>											
<i>eventSpeed</i>	Speed of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.										
<i>eventPositionHeading</i>	Heading of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.										
<i>traces</i>	<i>PathHistory</i> of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.										

	<p>If the PathDeltaTime is used in the PathPoints, the PathDeltaTime of the first PathPoint (closest point to the ReferencePosition) shall be refreshed for an update DENM. All other PathPoints shall not be refreshed. If the PathDeltaTime of the first PathPoint exceeds the maximum value in accordance with [TS 102 894-2], the PathDeltaTime shall not be further refreshed.</p> <p>If the PathDeltaTime is not used in the PathPoints, the PathHistory shall not be refreshed for an update DENM.</p>																					
<i>roadType</i>	<p><i>RoadType</i> of the road on which the detecting vehicle C-ITS station is situated.</p> <p>Shall be refreshed for an update DENM.</p> <p>Shall be set in accordance with [TS 102 894-2] in combination with the following rules:</p> <table border="1"> <thead> <tr> <th>Urban / non-urban</th> <th>Structural separation</th> <th>Data element</th> </tr> </thead> <tbody> <tr> <td>Urban</td> <td>No</td> <td>urban-NoStructuralSeparationToOppositeLanes(0)</td> </tr> <tr> <td>Urban</td> <td>Yes</td> <td>urban-WithStructuralSeparationToOppositeLanes(1)</td> </tr> <tr> <td>Urban</td> <td>Unknown</td> <td>urban-NoStructuralSeparationToOppositeLanes(0)</td> </tr> <tr> <td>Non-urban</td> <td>No</td> <td>nonUrban-NoStructuralSeparationToOppositeLanes(2)</td> </tr> <tr> <td>Non-urban</td> <td>Yes</td> <td>nonUrban-WithStructuralSeparationToOppositeLanes(3)</td> </tr> <tr> <td>Non-urban</td> <td>Unknown</td> <td>nonUrban-NoStructuralSeparationToOppositeLanes(2)</td> </tr> </tbody> </table> <p>Otherwise, if the information about the urban/non-urban status cannot be determined, the data element shall be omitted.</p>	Urban / non-urban	Structural separation	Data element	Urban	No	urban-NoStructuralSeparationToOppositeLanes(0)	Urban	Yes	urban-WithStructuralSeparationToOppositeLanes(1)	Urban	Unknown	urban-NoStructuralSeparationToOppositeLanes(0)	Non-urban	No	nonUrban-NoStructuralSeparationToOppositeLanes(2)	Non-urban	Yes	nonUrban-WithStructuralSeparationToOppositeLanes(3)	Non-urban	Unknown	nonUrban-NoStructuralSeparationToOppositeLanes(2)
Urban / non-urban	Structural separation	Data element																				
Urban	No	urban-NoStructuralSeparationToOppositeLanes(0)																				
Urban	Yes	urban-WithStructuralSeparationToOppositeLanes(1)																				
Urban	Unknown	urban-NoStructuralSeparationToOppositeLanes(0)																				
Non-urban	No	nonUrban-NoStructuralSeparationToOppositeLanes(2)																				
Non-urban	Yes	nonUrban-WithStructuralSeparationToOppositeLanes(3)																				
Non-urban	Unknown	nonUrban-NoStructuralSeparationToOppositeLanes(2)																				
<b>Alacarte Container</b>																						
<i>lanePosition</i>	<p>If the lanePosition is provided by an onboard sensor (e.g. radar, camera), the value shall be set in accordance with [TS 102 894-2]. Use of GNSS and a digital map for the estimation of the lane number is not legitimate for this version of the triggering condition.</p> <p>If the lanePosition is unknown, the data element shall be omitted.</p> <p>Shall be refreshed for an update DENM.</p>																					
<b>Alacarte container: StationaryVehicleContainer</b>																						

<i>stationarySince</i>	<p>Shall be set according to the duration in minutes of the detecting vehicle C-ITS station being stationary. Shall be set in accordance with [TS 102 894-2].</p> <p>Shall be refreshed for an update DENM.</p>
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Tested by:

### 3.2.7.2 CAM

#### Requirement (i)

RS\_tcSpVe\_154

The *vehicleRole* shall be initialised at a 'default' setting (*vehicleRole* of CAM set to *default(0)*). If at least one of the triggering conditions defined in RS\_tcSpVe\_240 is satisfied the *vehicleRole* shall be set to *emergency(6)*.

Tested by:

#### Requirement (i)

RS\_tcSpVe\_155

The following table specifies the data elements of the CAM that shall be set if the vehicle C-ITS service is triggered.

**Table 8: CAM data elements of 'stationary safeguarding emergency vehicle'**

Data field	Value
<b>CoopAwareness</b>	
<i>generationDeltaTime</i>	<p>Time corresponding to the time of the reference position in the CAM, considered as time of CAM generation.</p> <p>Shall be set in accordance with [EN 302 637-2].</p>
<b>BasicContainer</b>	
<i>stationType</i>	specialVehicles(10)
<i>referencePosition</i>	<p>Position and position accuracy measured at the reference point of the originating vehicle C-ITS station.</p> <p>Shall be set in accordance with [TS 102 894-2].</p>
<b>HighFrequencyContainer shall be set to BasicVehicleContainerHighFrequency</b>	
<i>heading</i>	<p>Heading direction of the originating vehicle C-ITS station in relation to true north.</p> <p>Shall be set in accordance with [TS 102 894-2].</p>
<i>speed</i>	<p>Driving speed of the originating vehicle C-ITS station.</p> <p>Shall be set in accordance with [TS 102 894-2].</p>
<i>driveDirection</i>	<p>Vehicle drive direction (forward or backward) of the originating vehicle C-ITS station.</p> <p>Shall be set in accordance with [TS 102 894-2].</p>
<i>vehicleLength</i>	<p>Length of vehicle.</p> <p>Shall be set in accordance with [TS 102 894-2].</p>

<i>vehicleWidth</i>	Width of vehicle. Shall be set in accordance with [TS 102 894-2].
<i>longitudinalAcceleration</i>	Vehicle longitudinal acceleration of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2].
<i>curvature</i>	Curvature of the vehicle trajectory and the accuracy. Shall be set in accordance with [TS 102 894-2].
<i>curvatureCalcMode</i>	Describes whether the yaw rate is used to calculate the curvature for a reported curvature value. Shall be set in accordance with [TS 102 894-2].
<i>yawRate</i>	Yaw rate of vehicle at a point in time. Shall be set in accordance with [TS 102 894-2].
<b>LowFrequencyContainer shall be set to BasicVehicleContainerLowFrequency</b>	
<i>vehicleRole</i>	emergency(6)
<i>exteriorLights</i>	Describes the status of the exterior light switches of a vehicle. Shall be set in accordance with [TS 102 894-2].
<i>pathHistory</i>	Represents the vehicle's movement over a recent period and/or distance. Shall be set in accordance with [TS 102 894-2].
<b>SpecialVehicleContainer shall be set to EmergencyContainer</b>	
<i>lightBarSirenInUse</i>	lightBarActivated bit shall be set to 1(onChange), if the usage of the light bar is detected, otherwise, it shall be set to 0. sirenActivated bit shall be set to 1, if usage of the siren is detected, otherwise, it shall be set to 0.
<i>emergencyPriority</i>	Is not required
<i>causeCode</i>	As specified in DENM (RS_tcSpVe_153)
<i>subCauseCode</i>	As specified in DENM (RS_tcSpVe_153)

Tested by:

### 3.2.8 Network and transport layer

#### Requirement (i)

RS\_tcSpVe\_156

The interface parameter destination area in IF.DEN.1 [ETSI EN 302 637-3] shall be equal to a circular shape with centre point equal to *eventPosition* and radius equal to *relevanceDistance*.

Tested by:

### 3.2.9 Security layer

#### Requirement (i)

RS\_tcSpVe\_158

When the triggering conditions as described in clause 3.2.2 apply, the application shall request the blocking of the AT changeover as defined in RS\_BSP\_184.

Tested by:

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### 3.3 Special vehicle warning - stationary recovery service warning

#### 3.3.1 Description of vehicle C-ITS service

**Other (informational)**

**RS\_tcSpVe\_229**

This vehicle C-ITS service supports a broken-down vehicle, i.e. standing on the right lane of the road representing a hazardous location. The vehicle C-ITS service of the moving recovery service, e.g. carrying a broken-down vehicle, is covered by the common CAM.

#### 3.3.2 Relations to other vehicle C-ITS services

**Other (informational)**

**RS\_tcSpVe\_230**

The following vehicle C-ITS services are related to this service, because they share similar triggering conditions:

- 'special vehicle warning — emergency vehicle in operation';
- 'special vehicle warning — stationary safeguarding emergency vehicle'.

#### 3.3.3 Triggering conditions

##### 3.3.3.1 Preconditions

**Requirement (i)**

**RS\_tcSpVe\_159**

The following preconditions shall be satisfied when this use case is triggered:

- the *stationType* is confirmed as an special vehicle (*stationType* of CAM is set to specialVehicles(10)). The vehicle C-ITS service is restricted to recovery service vehicles.

Tested by:

---

##### 3.3.3.2 Service-specific conditions

**Requirement (i)**

**RS\_tcSpVe\_160**

If the vehicle is stationary and the light bar is in use, a *Standstill Timer* shall be initialised with zero and started. If the light bar is no longer in use or the vehicle is no longer stationary, the *Standstill Timer* shall be stopped and reset to zero.

Tested by:

---

**Requirement (i)**

**RS\_tcSpVe\_241**

If the preconditions in RS\_tcSpVe\_159 and at least one of the following conditions are satisfied, the triggering conditions for this vehicle C-ITS service are fulfilled and the generation of a DENM shall be triggered:

- a) the light bar is in use, the hazard lights are activated and the parking brake is activated or (in the case of automatic transmission) 'park' is selected;

b) the light bar is in use, the hazard lights are activated and the *Standstill Timer* is 60 s or more.

Tested by:

---

**Requirement (i)**

**RS\_tcSpVe\_163**

The level of information quality can be improved by the following conditions:

- c) the status of driver door is 'open';
- d) the driver's seat is detected by one of the following techniques, as being 'not occupied':
  - a. passenger compartment camera;
  - b. state-of-the-art technique for seat occupation used in seatbelt reminder.

Tested by:

---

**Requirement (i)**

**RS\_tcSpVe\_164**

If the vehicle C-ITS service is triggered due to fulfilment of condition a), the *Standstill Timer* shall be stopped and set to 60 s. In the update phase, only the conditions shall be checked, but no timer shall be started.

Tested by:

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**3.3.3.3 Information quality**

**Requirement (i)**

**RS\_tcSpVe\_165**

The value of the data element *informationQuality* in the DENM depends on how the event is detected. The *informationQuality* value shall be set in accordance with the following table (highest possible value shall be used):

**Table 9: Information quality of 'stationary recovery service warning'**

Event detection	Value of InformationQuality
No TRCO-compliant implementation	unknown(0)
Condition b) fulfilled	1
Condition a) fulfilled	2
At least one of conditions a) or b) fulfilled and condition c) fulfilled	3
At least one of conditions a) or b) fulfilled and condition d) fulfilled	4

Tested by:

---

**Requirement (i)**

**RS\_tcSpVe\_166**

If the triggering conditions change between two updates, the *informationQuality* shall not be changed until the next update. If the changed conditions are still fulfilled while the DENM is updated, the *informationQuality* shall be updated.



Tested by:

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### 3.3.4 Termination conditions

#### Requirement (i)

RS\_tcSpVe\_167

This vehicle C-ITS service is terminated by a cancellation of the originating vehicle C-ITS station. At the termination of the vehicle C-ITS service, update DENM request shall be terminated.

Tested by:

---

#### 3.3.4.1 Cancellation

##### Requirement (i)

RS\_tcSpVe\_168

If the following condition is satisfied before the period set in the data element *validityDuration* has expired, the generation of a cancellation DENM shall be triggered and the *vehicleRole* shall be set to *default(0)*:

- vehicle C-ITS service-specific conditions a) and b) in clause 3.3.3.2 are not satisfied.

Tested by:

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#### 3.3.4.2 Negation

##### Requirement (i)

RS\_tcSpVe\_169

A negation DENM shall not be used for this vehicle C-ITS service.

Tested by:

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### 3.3.5 Update

#### Requirement (i)

RS\_tcSpVe\_170

The generated DENM shall be updated every 60 s if the triggering conditions are still satisfied. All data fields that are assigned new values are defined in RS\_tcSpVe\_153.

Tested by:

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### 3.3.6 Repetition duration and repetition interval

#### Requirement (i)

RS\_tcSpVe\_171

DENMs that are new, have been updated or have been cancelled shall be repeated for a *repetitionDuration* of 60 s with a *repetitionInterval* of 1 s. Therefore, the interface parameters *Repetition duration* and *Repetition interval* between the application and the DEN basic service shall be set in accordance with the above values.

Note: The *validityDuration* is set to 180 s. Therefore, one can prevent a gap of DENMs if the *repetitionDuration* of the original DENM has expired and the update has not yet been received.

Note: Where two DENMs with the same *causeCode* originate from the same vehicle C-ITS station, the case shall be managed by the receiving C-ITS station.

Tested by:

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### 3.3.7 Traffic class

**Requirement (i)**

RS\_tcSpVe\_172

New, update and cancellation DENMs shall be set to *traffic class* 1.

Tested by:

### 3.3.8 Message parameters

#### 3.3.8.1 DENM

**Requirement (i)**

RS\_tcSpVe\_173

The following table specifies the data elements of the DENM that shall be set.

**Table 10: DENM data elements of ‘stationary recovery service warning’**

Data field	Value										
<b>Management container</b>											
<i>actionID</i>	Identifier of a DENM. Shall be set in accordance with [TS 102 894-2].										
<i>detectionTime</i>	<i>Timestamp</i> ts-timestamp at which the event is detected by the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.										
<i>referenceTime</i>	<i>Timestamp</i> ts-timestamp at which a new DENM, an update DENM or a cancellation DENM is generated. Shall be set in accordance with [TS 102 894-2].										
<i>termination</i>	Shall not be set in case of new or update DENM. Shall be set to <i>isCancellation</i> (0) in case of fulfillment of cancellation conditions, see RS_tcSpVe_168.										
<i>eventPosition</i>	<i>ReferencePosition</i> . Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.										
<i>relevanceDistance</i>	lessThan5km(5)										
<i>relevanceTrafficDirection</i>	If the <i>roadType</i> is known the value shall be set as follows: <table border="1" style="margin-left: 20px;"> <thead> <tr> <th>RoadType</th> <th>Direction</th> </tr> </thead> <tbody> <tr> <td>0</td> <td><i>allTrafficDirections</i>(0)</td> </tr> <tr> <td>1</td> <td><i>upstreamTraffic</i>(1)</td> </tr> <tr> <td>2</td> <td><i>allTrafficDirections</i>(0)</td> </tr> <tr> <td>3</td> <td><i>upstreamTraffic</i>(1)</td> </tr> </tbody> </table> Otherwise, the value shall be set to <i>allTrafficDirections</i> (0)	RoadType	Direction	0	<i>allTrafficDirections</i> (0)	1	<i>upstreamTraffic</i> (1)	2	<i>allTrafficDirections</i> (0)	3	<i>upstreamTraffic</i> (1)
RoadType	Direction										
0	<i>allTrafficDirections</i> (0)										
1	<i>upstreamTraffic</i> (1)										
2	<i>allTrafficDirections</i> (0)										
3	<i>upstreamTraffic</i> (1)										
<i>validityDuration</i>	180 s										

<i>stationType</i>	specialVehicles(10)		
<b>Situation container</b>			
<i>informationQuality</i>	See RS_tcSpVe_165. Shall be refreshed for every update DENM.		
<i>causeCode</i>	rescueAndRecoveryWorkInProgress(15)		
<i>subCauseCode</i>	unavailable(0)		
<b>Location container</b>			
<i>eventSpeed</i>	Speed of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.		
<i>eventPositionHeading</i>	Heading of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.		
<i>traces</i>	<p><i>PathHistory</i> of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2]. Shall be refreshed for an update DENM.</p> <p>If the PathDeltaTime is used in the PathPoints, the PathDeltaTime of the first PathPoint (closest point to the ReferencePosition) shall be refreshed for an update DENM. All other PathPoints shall not be refreshed. If the PathDeltaTime of the first PathPoint exceeds the maximum value in accordance with [TS 102 894-2], the PathDeltaTime shall not be further refreshed.</p> <p>If the PathDeltaTime is not used in the PathPoints, the PathHistory shall not be refreshed for an update DENM.</p> <p>If the PathDeltaTime is not used in the PathPoints, the PathHistory shall not be refreshed for an update DENM.</p>		
<i>roadType</i>	<p><i>RoadType</i> of the road on which the detecting vehicle C-ITS station is situated. Shall be refreshed for an update DENM.</p> <p>Shall be set in accordance with [TS 102 894-2] in combination with the following rules:</p>		
	<b>Urban / non-urban</b>	<b>Structural separation</b>	<b>Data element</b>
	Urban	No	urban-NoStructuralSeparationToOppositeLanes(0)
	Urban	Yes	urban-WithStructuralSeparationToOppositeLanes(1)
Urban	Unknown	urban-NoStructuralSeparationToOppositeLanes(0)	

	Non-urban	No	nonUrban-NoStructuralSeparationToOppositeLanes(2)
	Non-urban	Yes	nonUrban-WithStructuralSeparationToOppositeLanes(3)
	Non-urban	Unknown	nonUrban-NoStructuralSeparationToOppositeLanes(2)
If the information about the urban/non-urban status cannot be determined, the data element shall be omitted.			
<b>Alacarte container</b>			
<i>lanePosition</i>	If the lanePosition is provided by an on-board sensor (e.g. radar, camera), the value shall be set in accordance with [TS 102 894-2]. Use of GNSS and a digital map to estimate the lane number is not legitimate for this version of the triggering condition.  If the lanePosition is unknown, the data element shall be omitted.  Shall be refreshed for an update DENM.		
<b>Alacarte Container: StationaryVehicleContainer</b>			
<i>stationarySince</i>	Shall be set according to the duration in minutes of the detecting vehicle C-ITS station being stationary. Shall be set in accordance with [TS 102 894-2].  Shall be refreshed for an update DENM.		

Tested by:

### 3.3.8.2 CAM

#### Requirement (i)

RS\_tcSpVe\_174

The *vehicleRole* shall be initialised at a 'default' setting (*vehicleRole* of CAM set to *default(0)*). If at least one of the triggering conditions defined in RS\_tcSpVe\_241 is satisfied the *vehicleRole* shall be set to *rescue(5)*.

Tested by:

#### Requirement (i)

RS\_tcSpVe\_175

The following table specifies the data elements of the CAM that shall be set if the vehicle C-ITS service is triggered.

**Table 11: CAM data elements of 'stationary recovery service warning'**

Data field	Value
<b>CoopAwareness</b>	
<i>generationDeltaTime</i>	Time corresponding to the time of the reference position in the CAM, considered as time of the CAM generation.

	Shall be set in accordance with [EN 302 637-2].
<b>BasicContainer</b>	
<i>stationType</i>	specialVehicles(10)
<i>referencePosition</i>	Position and position accuracy measured at the reference point of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2].
<b>HighFrequencyContainer shall be set to BasicVehicleContainerHighFrequency</b>	
<i>heading</i>	Heading direction of the originating vehicle C-ITS station in relation to true north. Shall be set in accordance with [TS 102 894-2].
<i>Speed</i>	Driving speed of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2].
<i>driveDirection</i>	Vehicle drive direction (forward or backward) of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2].
<i>vehicleLength</i>	Length of vehicle. Shall be set in accordance with [TS 102 894-2].
<i>vehicleWidth</i>	Width of vehicle. Shall be set in accordance with [TS 102 894-2].
<i>longitudinalAcceleration</i>	Vehicle longitudinal acceleration of the originating vehicle C-ITS station. Shall be set in accordance with [TS 102 894-2].
<i>curvature</i>	Curvature of the vehicle trajectory and the accuracy. Shall be set in accordance with [TS 102 894-2].
<i>curvatureCalcMode</i>	Describes whether the yaw rate is used to calculate the curvature for a reported curvature value. Shall be set in accordance with [TS 102 894-2].
<i>yawRate</i>	Yaw rate of vehicle at a point in time. Shall be set in accordance with [TS 102 894-2].
<b>LowFrequencyContainer shall be set to BasicVehicleContainerLowFrequency</b>	
<i>vehicleRole</i>	rescue(5)
<i>exteriorLights</i>	Describes the status of the exterior light switches of a vehicle. Shall be set in accordance with [TS 102 894-2].
<i>pathHistory</i>	Represents the vehicle's movement over a recent period and/or distance. Shall be set in accordance with [TS 102 894-2].
<b>SpecialVehicleContainer shall be set to SafetyCarContainer</b>	

<i>lightBarSirenInUse</i>	lightBarActivated bit shall be set to 1(onChange) if the usage of the light bar is detected; otherwise, it shall be set to 0. sirenActivated bit shall be set to 1 if usage of the siren is detected; otherwise, it shall be set to 0.
<i>causeCode</i>	As specified in DENM (RS_tcSpVe_173)
<i>subCauseCode</i>	As specified in DENM (RS_tcSpVe_173)

Tested by:

### 3.3.9 Network and transport layer

#### Requirement (i)

**RS\_tcSpVe\_176**

The interface parameter destination area in IF.DEN.1 [ETSI EN 302 637-3] shall be equal to a circular shape with centre point equal to *eventPosition* and radius equal to *relevanceDistance*.

Tested by:

### 3.3.10 Security layer

#### Requirement (i)

**RS\_tcSpVe\_178**

When the triggering conditions as described in clause 3.3.3 apply, the application shall request the blocking of the AT changeover as defined in RS\_BSP\_184.

Tested by:

## 4 Appendix

### 4.1 Scenarios

Other (informational)

RS\_tcSpVe\_232

This clause has an informational character and is not part of the requirement specification.

The following list encompasses scenarios which are regarded as relevant or irrelevant considering the present vehicle C-ITS service:

Count	Description	Status
SC_0	Urban/nonurban environment	Irrelevant
SC_1	Current road situation and conditions	Not directly relevant
SC_2	Traffic in the opposite driving direction.	Irrelevant
SC_3	The special vehicle drives to an emergency site using the light bar. The sirene might be used.	Relevant
SC_4	The special vehicle stops at an emergency site in order to safeguard the situation. The intention of the special vehicle and the crew has to be detected. A change in the use-cases from 'in operation' to 'safeguarding' has to be detected.	Relevant
SC_5	The special vehicle leaves an emergency site. A change in the use-cases from 'safeguarding' to 'in operation' might be detected depending on situation.	Relevant
SC_6	The recovery service carries a broken vehicle using the light bar. This case is covered by usual CAMs. The recovery service is considered as a usual vehicle in road traffic.	Irrelevant

**Table 12: Scenarios**